# MINHYUK JANG

■ jason4012@snu.ac.kr in <u>LinkedIn</u> Google Scholar Ajangminhyuk.github.io

## Education

# Seoul National University (SNU)

Mar. 2019 - Feb. 2025

B.S. in Mechanical Engineering (Robotics Track), Interdisciplinary Major in Artificial Intelligence

- Summa Cum Laude (GPA: 3.99/4.0), Outstanding B.S. Thesis Presentation Award
- Relevant Coursework: Nonlinear System Theory (Graduate, A+), Advanced Control Techniques (A+)
- 18 months of military service included

## Research Interests

- Control Theory (Robust Control, Optimal Control, Learning-Based Control, Adaptive Control, Nonlinear Control)
- Safety Guarantee, Safety-Critical Systems (Multirotor, VTOL, Robotics, etc.), Multi-Agent Systems

## **Publications**

- Minhyuk Jang, Astghik Hakobyan, and Insoon Yang. On the Steady-State Distributionally Robust Kalman Filter, IEEE Control and Decision Conference (CDC), (submitted), [arXiv]
- Minhyuk Jang, Astghik Hakobyan, and Insoon Yang. Distributionally Robust Control and State Estimation for Linear Stochastic Systems, IEEE Transactions on Automatic Control (TAC), (under review), [arXiv]
- Minhyuk Jang. Stability Analysis of Disturbance Observer under Model Uncertainty with Different System Degrees between True and Nominal Systems, Institute of Control, Robotics and Systems (ICROS), 2024

# Experience

# SNU Control and Optimization Research (CORE) Lab

Mar. 2023 - PRESENT

Research Intern - Advisor: Prof. Insoon Yang

Seoul, South Korea

- Developed unified algorithm for <u>Distributionally Robust Control and State Estimation</u>, a game-theoretic approach to stochastic optimal control handling inaccurate data-driven disturbances and noise distributions
- Formulated a tractable semidefinite programming problem that iteratively determines the worst-case covariance matrices of all uncertainties, significantly enhancing the scalability and efficiency of the proposed algorithm

NEARTHLAB Jan. 2024 – Feb. 2024

Aerospace Engineering Intern, GNC Team

Seoul, South Korea

- Implemented DOB and LQR based position/velocity controllers in C++&ROS2 and tested through Gazebo simulation
- Integrated a flight controller with a companion computer for quadrotor offboard control, implemented DOB+LQR and DOB+PID trajectory tracking controllers, and conducted extensive outdoor flight experiments

## Selected Projects (See more at HERE)

## Automated Hyperparameter Tuning Algorithm for MPPI Control

Sep. 2023 – Jun. 2024

Outstanding B.S. Thesis Presentation Award

Seoul, South Korea

- Designed an adaptive algorithm to automatically adjust the hyperparameter (Inverse temperature) for MPPI control
- Implemented the algorithm in the MuJoCo MPC (MJPC) framework, improving control performance, reducing state fluctuations and control costs, and enabling smoother trajectories in quadrotor hovering and racing tasks

## VTOL (Vertical Take-off and Landing) Projects

Mar 2024 - Sep 2024

Team Leader - Korea Robot Aircraft Competition (Grand Award)

Taean. South Korea

- Constructed two A-tail Quadplane VTOLs with autonomous flight capabilities, each with wingspans of 1.5m and 2.0m
- Oversaw the full system engineering process, from selecting electronic components (servos, motors, flight controller, batteries, GPS, PDB, RC, etc.) to wiring, sensor calibration, and mission task planning

## AIAA Design/Build/Fly (DBF) Competition

Sep. 2024 - PRESENT

Control Team

Tucson, AZ, USA (2025)

- Developed landing algorithm for a glider launched from a mothership at a 100m altitude, with a 250g weight limit
- Modified and tested Ardupilot soaring algorithm, followed by outdoor flight experiments to validate performance and ensure accurate landing on a target location

# Leadership / Extracurricular activities

#### Bulnabi - SNU Drone Club

Sep. 2023 - PRESENT

Team Leader

Seoul, South Korea

- Organized and conducted over five Quadrotor Build/Fly seminars, teaching hardware assembly, sensor calibration, Ground Control Station usage, flight experiments, and flight log analysis
- Led a 25-member team for the Korea Robot Aircraft Competition, focusing on VTOL system design and autonomous flight missions; conducted over 30 outdoor fixed-wing missions and successfully stabilized all flight phases.

# KATUSA (Korean Augmentation to the United States Army)

Sep. 2021 - Mar. 2023

Squad Leader - Sergeant, 8th Army, Camp Humphreys

Pyeongtaek, South Korea

- Led and managed a 10-solider squad, ensuring their training, well-being, and mission preparedness
- Provided essential translation and interpretation support during Combined Exercises, leveraging language proficiency
- Engaged in daily collaboration with American colleagues within a U.S. Army office

# G.I.V - SNU Volunteering Club

Mar. 2019 - Sep. 2020

Vice President

Seoul, South Korea

- Delivered educational support in math, science, and art to teenagers in rural areas, emphasizing experiential learning
- Organized and engaged in various volunteer activities, including secondhand markets, mural painting, and food drives

## **Talks**

- Invited Talks: Design and Development of a Lightweight, 3D-Printed VTOL Aircraft with Autonomous Flight Capabilities, Center for Scientific Innovation and Education (CSIE), Yerevan, Armenia, 2024, (online)
- Invited Talks: Design and Development of a Lightweight, 3D-Printed VTOL Aircraft with Autonomous Flight Capabilities for Advanced Air Mobility (AAM), Unmanned Vehicle Systems Symposium, Daejeon, South Korea, 2024

# Honors / Awards

# College of Engineering Outstanding Graduate Award

2025

One of the Top 24 Graduates across the entire College of Engineering

SNU College of Engineering Alumni Association

## Grand Award - Korea Robot Aircraft Competition

2024

1st Place among 39 University Teams

Minister of Commerce, Industry and Energy

#### Outstanding B.S. Thesis Presentation Award

2024

Department of Mechanical Engineering

Seoul National University

# Outstanding Materials and Manufacturing Processes Award

2024

Materials and Manufacturing Processes Contest

Seoul National University

## **Excellence Award - Mechatronics Competition**

2020

Department of Mechanical Engineering

Seoul National University

## ARCOM (Army Commendation Medal)

2022

United States Department of the Army

Camp Humphreys

#### Kwanjeong Scholarship

2021

Recipient of a full tuition scholarship along with a stipend for two years

Kwanjeong Educational Foundation

## Merit-based Scholarship

Spring 2020, Fall 2020

Department of Mechanical Engineering

Seoul National University

## **Technical Skills**

**Programming:** C/C++, Python, MATLAB (Simulink)

Libraries/Softwares: PX4-Autopilot, ROS2, Gazebo, Arduino, MuJoCo, PyTorch, Fusion 360, SolidWorks, IATEX

Hardware Skills: Drone operation, FPV drone piloting, soldering and wiring, laser cutting, 3D printing